# PilotStar D

Heading Control System



## PilotStar D

Anschütz PilotStar D is the professional autopilot recommended for all classes of ships up to a length of 120 m. Due to most advanced steering algorithms PilotStar D is well known in the market for its excellent steering performance, accuracy and reliability.

PilotStar D is used in heading or waypoint steering control in combination with an external navigation receiver. It can easily be adapted manually or by predefined parameter sets to the current environmental or ship condition and adapts automatically to ships speed. A constant rudder trim can be defined to compensate for drift. FIX TURN allows to perform a definable heading change to port or starboard by simply clicking a button – an important feature for workboats.

PilotStar D offers various interfaces that make an installation on newbuildings and retrofit applications quick and simple. Heading is input from magnetic compass (as NMEA telegram or via magnetic compass sonde) and gyro compass. Speed information is input as pulse or serial telegram. In addition the autopilot provides an interface for a central alarm system. An alarm is transferred to the central alarm panel and can be muted remotely. A steering repeater can be connected directly to PilotStar D to display both, the heading of magnetic or gyro compass.



- Accurate steering
- Reliable technology installed on thousands of ships
- Ease of use and clear data display
- Remote operator units
- Type approved as heading control system
- Type approved as heading control system for high-speed craft

The operator unit provides clear indication of all necessary data and ease of use

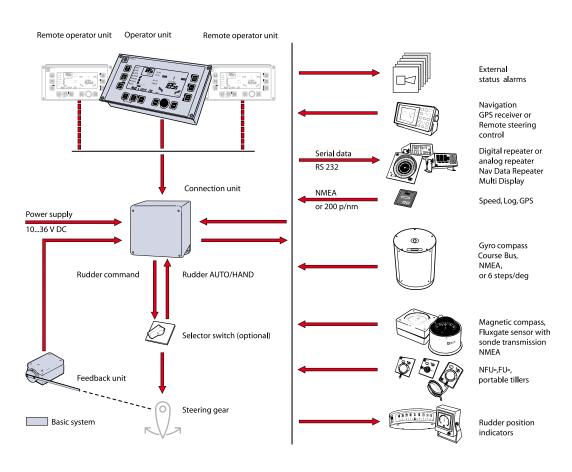






## Flexible System Configuration

The Anschütz PilotStar D is a versatile autopilot used in various system environments such as steering gears with switching and proportional solenoids, twin-rudders, rudder propellers and water jet drives. The PilotStar D can be extended by remote operator units, follow-up and non-follow-up tillers. These tillers are equipped with a take-over function to take over the control from the autopilot. Thus a remote steering control system is easily set up.









## **Technical Data**

#### Supply voltage

24 V DC (10-36 V DC)

#### **Power consumption**

Approx. 15 W

#### Signal inputs

#### Gyro compass / satellite compass

- Course BusNMEA telegrams HEHDT, GPHDT (9600 Bd)
- 6 steps per degree

#### Magnetic compass

- NMEA telegram IIHDM, HCHDM
  With magnetic compass sonde 108-010
- Fluxgate sonde sine/cosine

### Speed log

- NMEA telegrams VTG, VHW200 pulses/nm

#### Navigation receiver

- NMEA telegrams APA, APB, XTERemote control with NMEA telegram HSC

#### Signal outputs

Outputs to steering gear

- 2 switching outputs (110 V DC 0.5 A; 24 V DC 2.0 A)
   2 analog outputs (+/- 10 V DC max. 5 mA)

#### Status/alarm outputs

- Off-headingCourse monitor
- System failure
- Power failure
- Steering failure monitoring
- Bi-directional central alarm reset (optional)
- Tiller ON

#### In accordance with

- ISO 11674
- NMEA according to EN/IEC 61162
- EN/IEC 60945
- A.342(IX), A.694(17), MSC.64(67) Annex 3, A.822(19) For details refer to EC-type examination certificate.

#### Type of enclosure acc. to IEC/EN 60529

- Operator unit: IP 56 (mounted)
- Connection unit: IP 22

#### Permissible ambient temperature

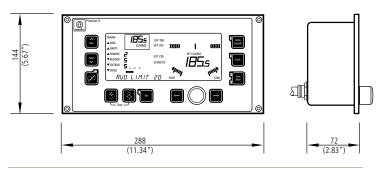
Operation: -15°C to + 55°C (operator unit)

-15°C to + 55°C (connection unit)

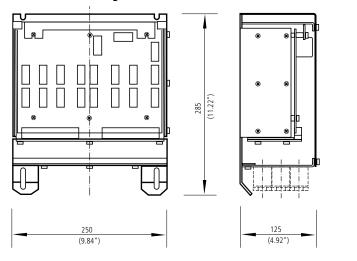
-25°C to + 70°C (operator unit) – Storage:

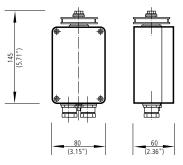
-25°C to + 70°C (connection unit)

#### Operator unit 2.0 kg

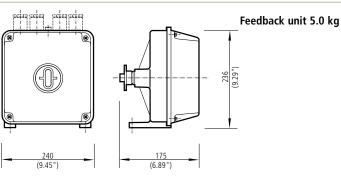


#### Connection unit 5.5 kg





#### Feedback unit 0.9 kg



Raytheon Anschütz GmbH