

Simrad MX521B

D/GNSS (GPS+GLONASS) SMART ANTENNA

- IMO Compliant GPS/DGPS sensor with GLONASS*
- Enhanced position performance with GLONASS
- Flexibility for easy integration into NMEA 0183 interface
- RAIM (Receiver Autonomous Integrity Monitoring) enabled
- Meets Smart Beacon specifications for DGPS Smart Antenna
- Connects directly to Simrad Control and Display Unit
- Better than 1 meter DGPS Position accuracy
- Better than 3 meter GPS position accuracy
- Built-in DGPS source include SBAS (WAAS, EGNOS, MTSAT)
- D/GPS mode compatibility with MX420/MX510 and MX512 CDU
- * SIMRAD CDU is required to comply as an IMO approved system

DGPS SMART ANTENNA

The MX521B delivers position accuracy better than 1 meter in DGPS/DGNSS mode when using RTCM corrections.

BEACON

Navigation authorities around the world have installed DGPS readiobeacon networks that broadcast RTCM corrections. With the use of its built-in beacon demodulator, the MX521B uses these real-time corrections to deliver accurate, reliable positioning when antenna is within range of Beacon station.

RAIM

Receiver Autonomous Integrity Monitoring (RAIM) is a safety feature in the MX521B which continuously verifies the integrity of the GPS system to ascertain its' accuracy and reliability.

SIMRAD MX521B Smart Antenna



MX610/MX612 CDU

When satellite range error exceeds a pre-set limit, the CDU alerts the operator to take precautionary measures.

INTERFACE

The MX521B features two independent NMEA compliant serial ports which are identical to MX421B-10 and MX521A DGPS smart antenna

Technical specifications overleaf.





Wheelmark Approved

www.navico.com/commercial

Technical Specifications

GNSS SENSOR SPECIFIC	ATIONS	
Receiver Type:	GNSS L1 Receiver	
Signals Received:	GPS, GLONASS	
Channels:	270	
GPS Sensitivity:	-142 dBm	
SBAS Tracking:	2-channel, parallel tracking	
Update Rate:	10 Hz standard	
POSITIONING ACCURAC	ΣΥ	
RMS:	Horizontal	
Single Point: 1	3 m	
SBAS (WAAS): 2	1 m	
Code Differential DGPS: ²	1 m	
COMPASS SAFE		
Distance:	75 cm (with enclosure) ³	
Cold Start:	60 s (no almanac or RTC)	
Warm Start:	20 s typical (almanac and RTC)	
Hot Start:	1 s typical (almanac, RTC and position)	
Heading Fix:	10 s typical (valid position)	
Maximum Speed:	1,850 mph (999 kts)	
Maximum Altitude:	18,288 m (60,000 ft)	
BEACON SENSOR SPECI	FICATIONS	
Channels:	2-channel, parallel tracking	
Frequency Range:	283.5 to 325 kHz	
Operating Modes:	Manual, automatic and database	
Compliance:	IEC 61108-4 beacon standard	
COMMUNICATIONS		
Baud Rates:	4800 - 38400	
Correction I/O Protocol:	RTCM v2.3 (DGPS)	
Data I/O Protocol:	NMEA 0183	
POWER		
Input Voltage:	10.5 to 32 VDC	
Power Consumption:	4.3 W nominal (GPS L1 + GLONASS L1) 4.6 W nominal (GPS L1 + GLONASS L1 + Beacon)	
Current Consumption:	0.36 A nominal (GPS L1 + GLONASS L1) 0.38 A nominal (GPS L1 + GLONASS L1 + Beacon)	
Power Isolation:	Isolated to enclosure	
Reverse Polarity Protection:	Yes	

DIST	RIBU	TED	BY:

ENVIRONMENTAL		
Operating Temperature:	-30°C to + 70°C (-22°F to + 158°F)	
Storage Temperature:	-40°C to + 85°C (-40°F to + 185°F)	
Humidity:	95% non-condensing	
Shock and Vibration:	Mechanical Shock: EP455 Section 5.14.1 Vibration: EP455 Section 5.15.1 Random	
EMC:	CE (IEC 60945 Emissions and Immunity) FCC Part 15, Subpart B CISPR22	
IMO Wheelmark Certification:	Yes ⁶	
MECHANICAL	·	
Power/Data Connector:	10-pin, environmentally sealed	

▶ SPECIFIED STANDARD(S) IMO Resolution MSC.112(73) IEC 61108-1 Ed.2.0, 2003 IMO Resolution MSC.113(73) IEC 61108-2 Ed.1.0, 1998 IMO Resolution MSC.114(73) IEC 61108-4 Ed.1.0, 2004 IMO Resolution MSC.115(73) IEC 60945 Ed.4.0, 2002 incl. Corr. 1, 2008 IMO Resolution A.694(17) IEC 61162-1 Ed.4.0, 2010 IMO Resolution MSC.191(79) IEC 62288 Ed.1.0, 2008 IEC 61162-3 Ed.1.1 2010 (NMEA 2000) IEC 61162-3 Ed.1.1 2010 (NMEA 2000)

¹ Depends on multipath environment, number of satellites in view, satellite geometry, no SA, and ionospheric activity

 $^{\rm 2}$ Depends on multipath environment, number of satellites in view, WAAS coverage and satellite geometry

³ This is the minimum safe distance measured when the product is placed in the vicinity of the steering magnetic compass. The ISO 694 defines "vicinity" relative to the compass as within 5m (16.4 ft) separation

4 NMEA 0183 only



